

Symmetry OperationsMatrix representation: a few examples	Reflection
Identity Inversion $E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ $I = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$	$\sigma_z = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ reflection in <i>x-y</i> plane
Rotationrotation about the z-axis $C_n = \begin{pmatrix} \cos 2\pi / n & \sin 2\pi / n & 0 \\ -\sin 2\pi / n & \cos 2\pi / n & 0 \\ 0 & 0 & 1 \end{pmatrix}$	$\sigma_x = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ reflection in <i>y-z</i> plane
Rotary-reflectionrotation about the z-axis then reflection in x-y $S_{nz} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \cos 2\pi/n & \sin 2\pi/n & 0 \\ -\sin 2\pi/n & \cos 2\pi/n & 0 \\ 0 & 0 & 1 \end{pmatrix} = $	$\begin{pmatrix} \cos 2\pi/n & \sin 2\pi/n & 0 \\ -\sin 2\pi/n & \cos 2\pi/n & 0 \\ 0 & 0 & -1 \end{pmatrix}$



















